

**AMENDMENTS TO THE CLAIMS:**

Please amend claims 3, 4, and 29, as denoted in the following listing. This listing of claims will replace all prior versions and listings of claims in the application:

1. (Previously amended) A system for capturing information about objects moving relative to the system comprising:

an object dimensioning system for producing time-dependent dimension information for each of the objects as each object moves relative to the dimensioning system;

an object identification system for producing object identification information for the objects; and

an image capture system for producing time-dependent images of the objects.

2. (Original) The system of claim 1, wherein the objects are parcels.

3. (Currently amended) The system of claim 1, wherein the object dimension information, object identification information, and ~~electronic~~ images each have time stamp information associated therewith.

4. (Currently amended) The system of claim 1, wherein object dimension information, object identification information, and ~~electronic~~ images of an object are correlatable based on the time stamp information.

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5. (Original) The system of claim 1, wherein the object identification system comprises at least one bar code scanner.

6. (Original) The system of claim 5, wherein object dimension information associated with an object is correlated to object identification information associated with the same object using information about a scan pattern produced by the bar code scanner and time stamp information.

7. (Original) The system of claim 1, wherein the object dimensioning system comprises at least one vertical height scanner.

8-28. (Withdrawn)

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29. (Currently amended) A system, including transport means, for capturing information about objects moving ~~along~~ on the transport means relative to the system comprising:

a position system for providing positional information associated with the transport means;

an object dimensioning system for producing dimension information for the objects;

orientation means for determining an orientation of each object on the transport means using at least the positional information;

~~an object identification system for producing identification information for the objects~~

information capture means for obtaining information from each object, wherein the image capture means includes a plurality of scanning means and wherein each scanning means is simultaneously focused based on the orientation of the objects on the transport means;

an image capture system for producing images of the objects; and

at least one processor for associating time values with the positional information and computing models of the objects using the positional information and the dimension information.